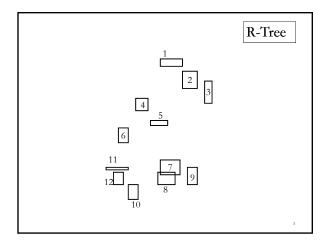
Nearest Neighbor Queries

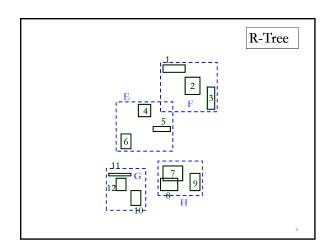
Nick Roussopoulos, Stephen Kelly and Frédéric Vincent

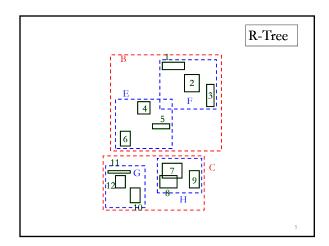
Ling Hu lingh@usc.edu

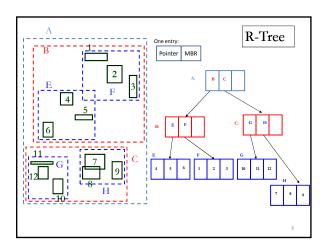
Outline

- Spatial Index R-Tree
- NN query Naïve solution
- A better solution Branch-and-bound
- Can we do better?
- Experiment Results









Outline

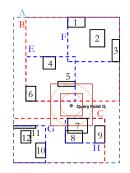
- Spatial Index R-Tree
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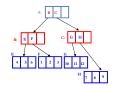
Nearest Neighbor Search

- Retrieve the nearest neighbor of query point Q
- · Simple Strategy:
 - convert the nearest neighbor search to range search.
 - Guess a range around Q that contains at least one object say O
 - if the current guess does not include any answers, increase range size until an object found.
 - Compute distance d' between Q and O
 - re-execute the range query with the distance d' around Q.
 - Compute distance of Q from each retrieved object. The object at minimum distance is the nearest neighbor!!!

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Naïve Approach





Issues: how to guess range?
The retrieval may be sub-optimal if incorrect range guessed.
Would be a problem in high dimensional spaces.

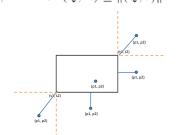
Outline

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MINDIST Property

• MINDIST is a lower bound of any k-NN distance $\forall o \in O, \text{MINDIST}(Q,R) \leq \|(Q,o)\|$

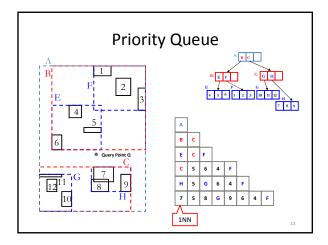


A Better Strategy for KNN search

- A sorted priority queue based on MINDIST;
- Nodes traversed in order;
- Stops when there is an object at the top of the queue; (1-NN found)
- k-NN can be computed incrementally;

I/O optimal

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Outline

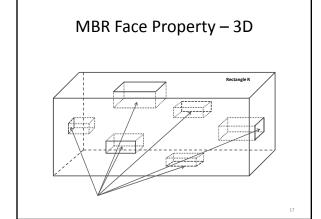
- Spatial Index R-Tree
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MBR Face Property

- MBR is an n-dimensional Minimal Bounding Rectangle used in R trees, which is the minimal bounding n-dimensional rectangle bounds its corresponding objects.
- MBR face property: Every face of any MBR contains at least one point of some object in the database.





Improving the KNN Algorithm

 While the MinDist based algorithm is I/O optimal, its performance may be further improved by pruning nodes from the priority queue.

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Properties of MINMAXDIST

- MINMAXDIST(P,R) is the minimum over all dimensions distances from P to the furthest point of the closest face of R.
- MINMAXDIST is the smallest possible upper bound of distances from the point P to the rectangle R.
- MINMAXDIST guarantees there is an object within the R
 at a distance to P less than or equal to it.

 $\exists o \in O, ||(Q, o)|| \le MINMAXDIST(Q, R)$

• MINMAXDIST is an upper bound of the 1-NN distance

MINDIST & MINMAXDIST

MINDIST(P,R) <= NN(P) <= MINMAXDIST(P,R)

MER

HIMMAXDIST

HIMMAXDIST

HIMMAXDIST

HIMMAXDIST

HIMMAXDIST

HIMMAXDIST

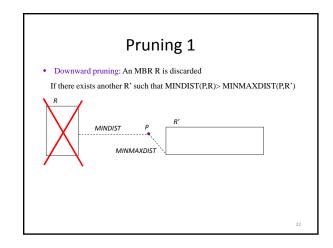
HIMMAXDIST

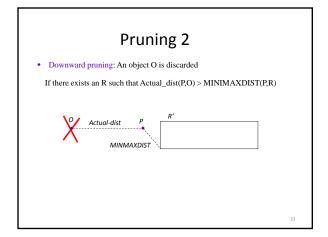
ALINDIST

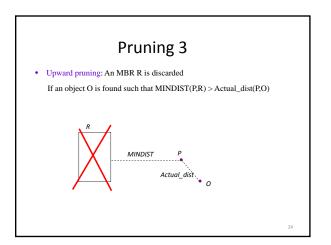
ALINDIST

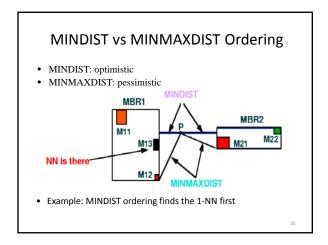
ALINDIST

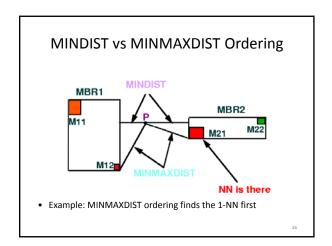
MinDist & MinMaxDist — 3D Query Point Q MinDist(Q,R) Rectangle R





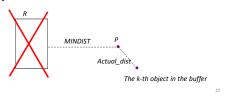






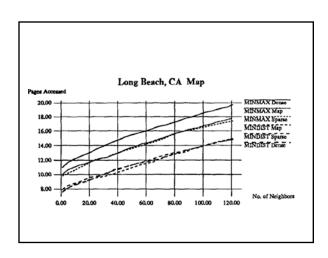
Generalize to k-NN

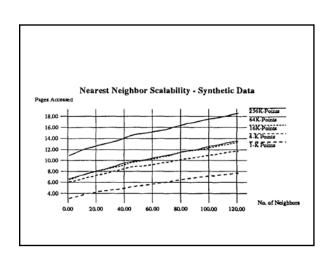
- Keep a sorted buffer of at most *k* current nearest neighbors
- Pruning is done according to the distance of the furthest nearest neighbor in this buffer
- Example:

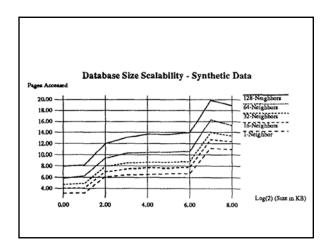


Outline

- Spatial Index R-Tree
- NN Query Intuitive Solutions
- Optimized NN Query branch-and-bound
- Experiment Results







Key Insights

- # of pages accessed grows when k grews;
- The denser the dataset, the more page access;
- MinDist v.s. MinMaxDist: same in shape, but MinMaxDist has more I/O cost;
- In Dense area, MinMaxDist is bad;

